

FIG. 1

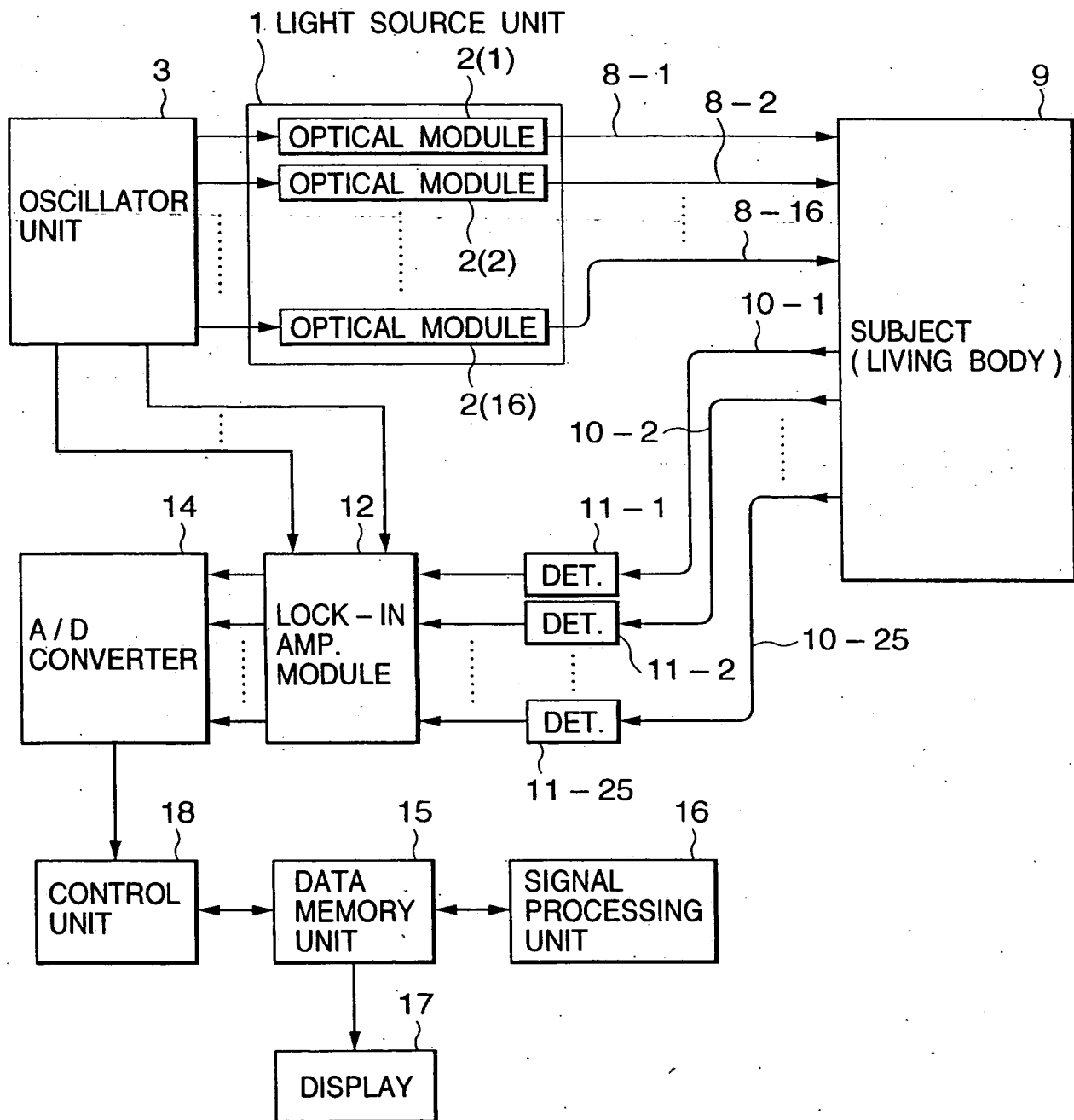


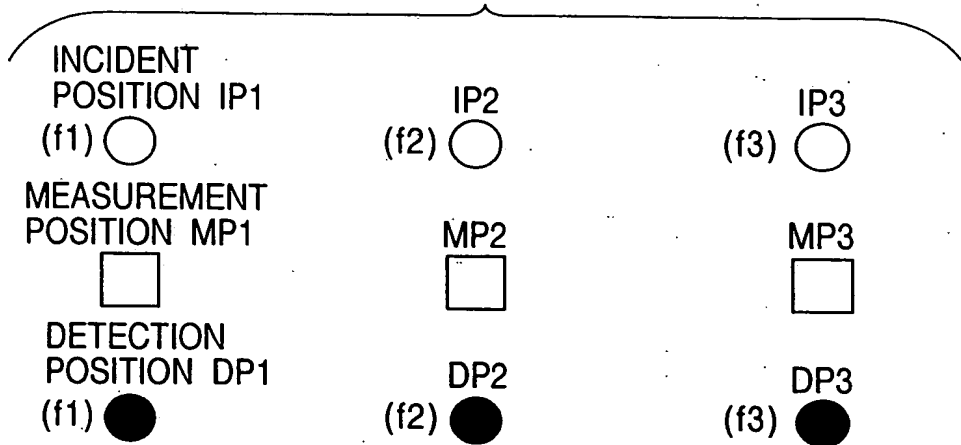
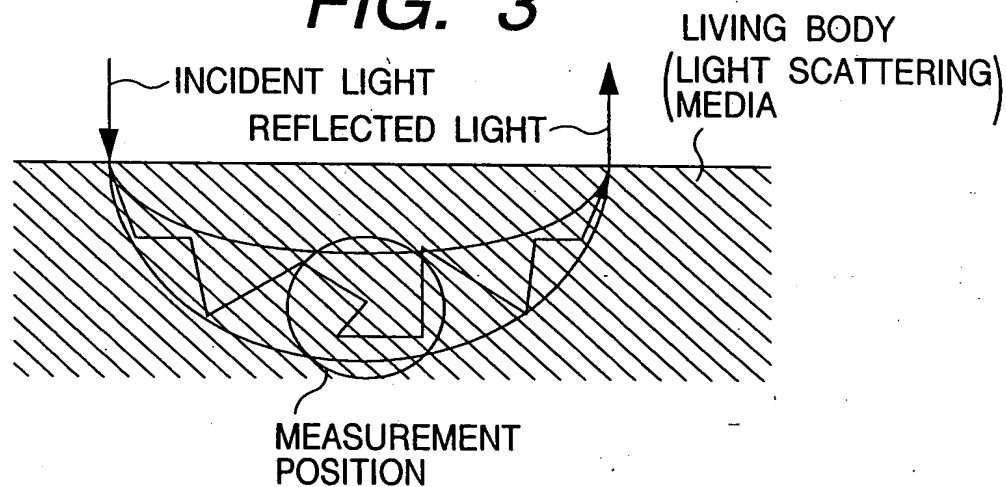
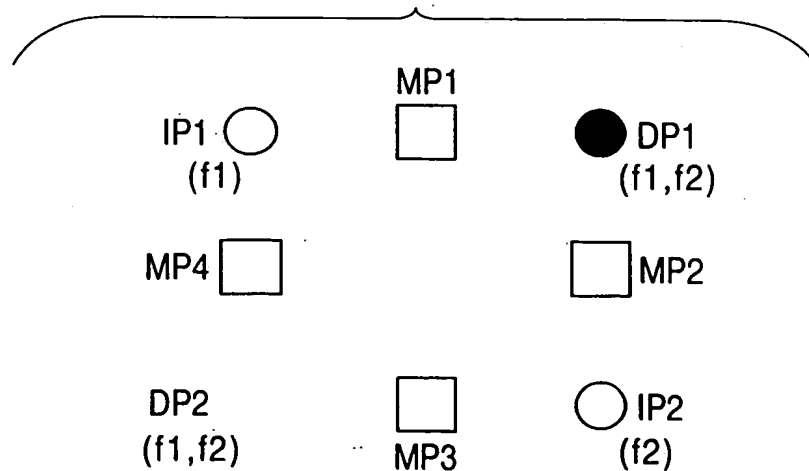
FIG. 2**FIG. 3****FIG. 4**

FIG. 5

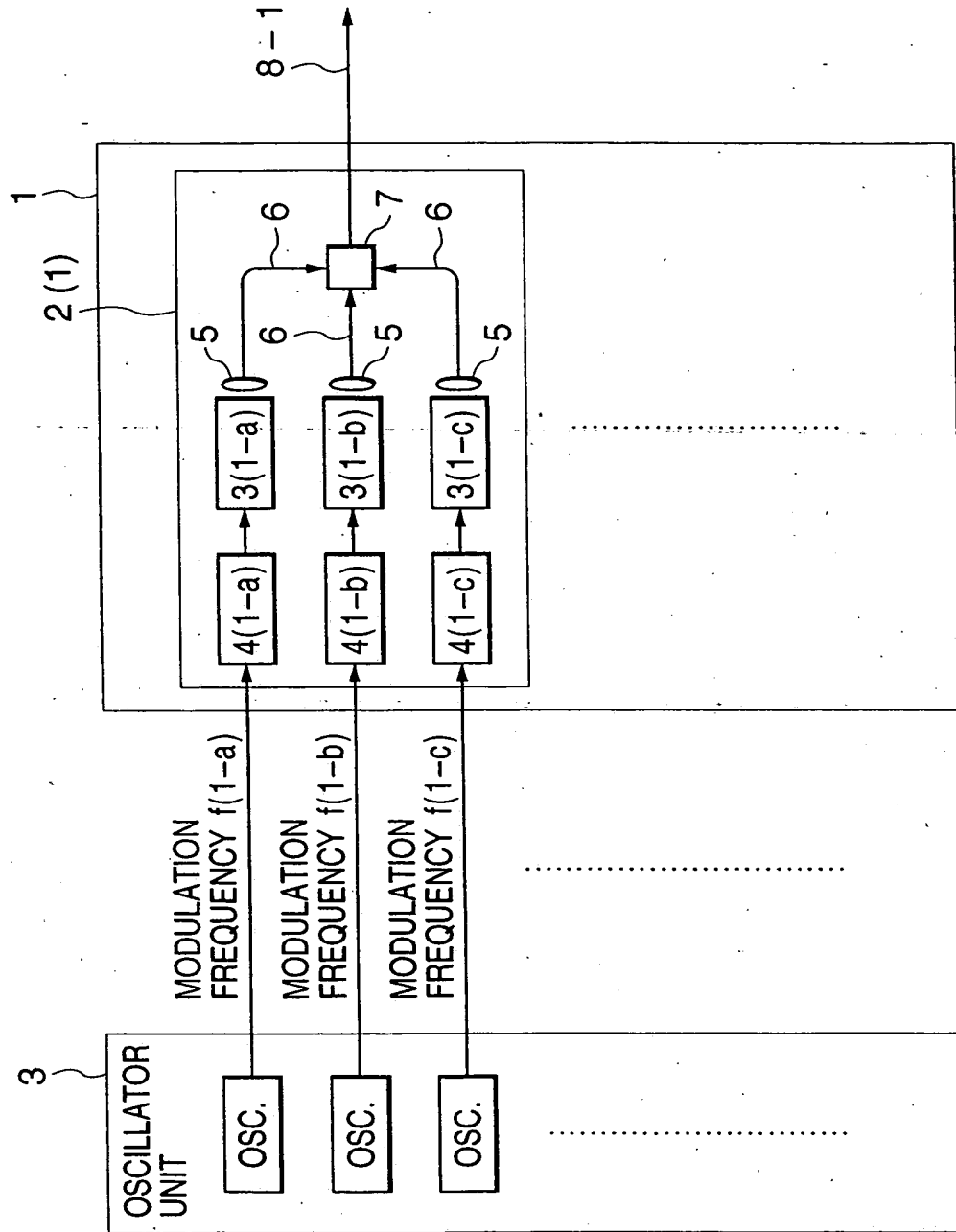
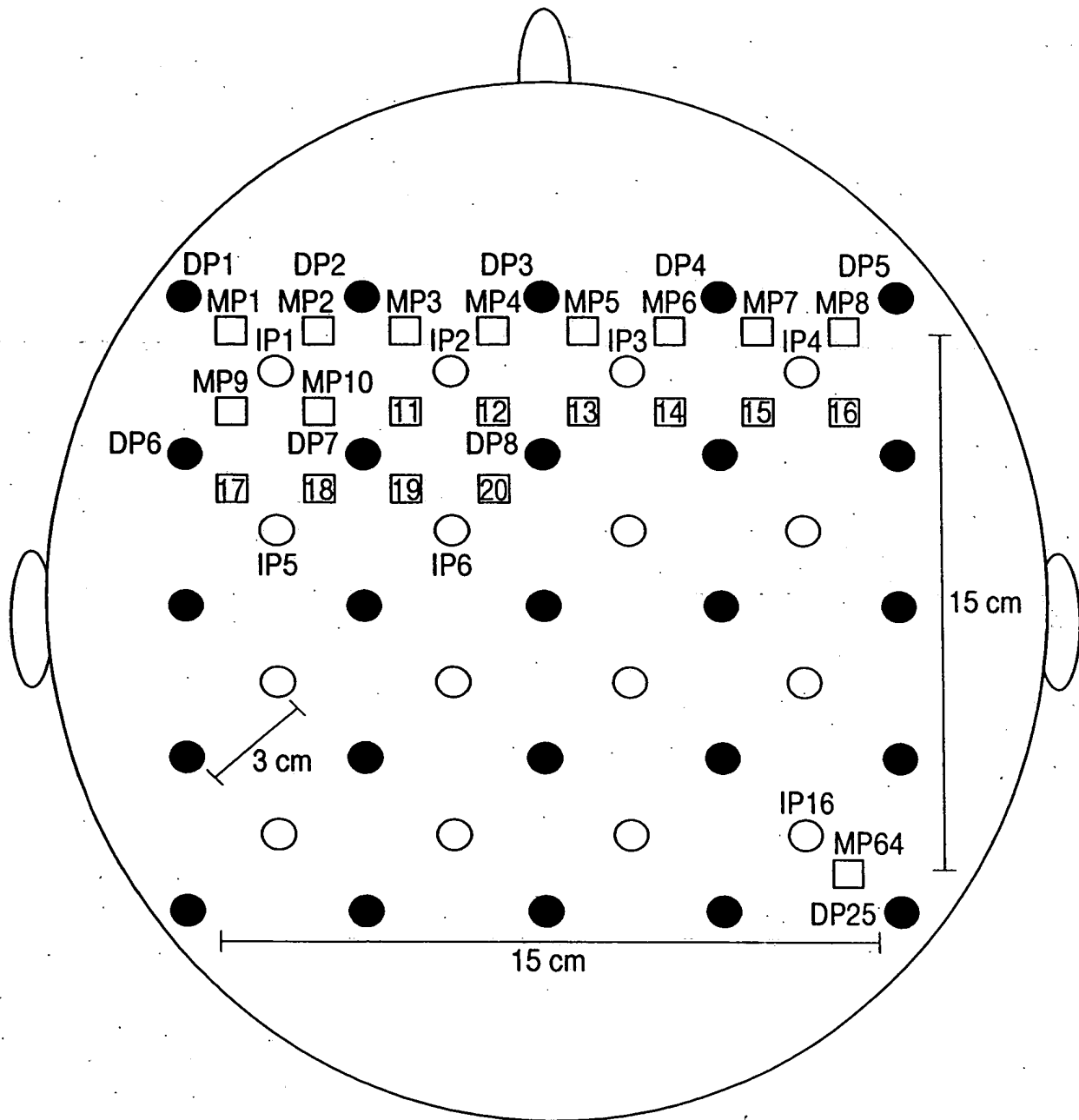


FIG. 6



○ INCIDENT POSITION (IP) ● DETECTION POSITION (DP)
 □ MEASUREMENT POSITION (MP)

FIG. 7

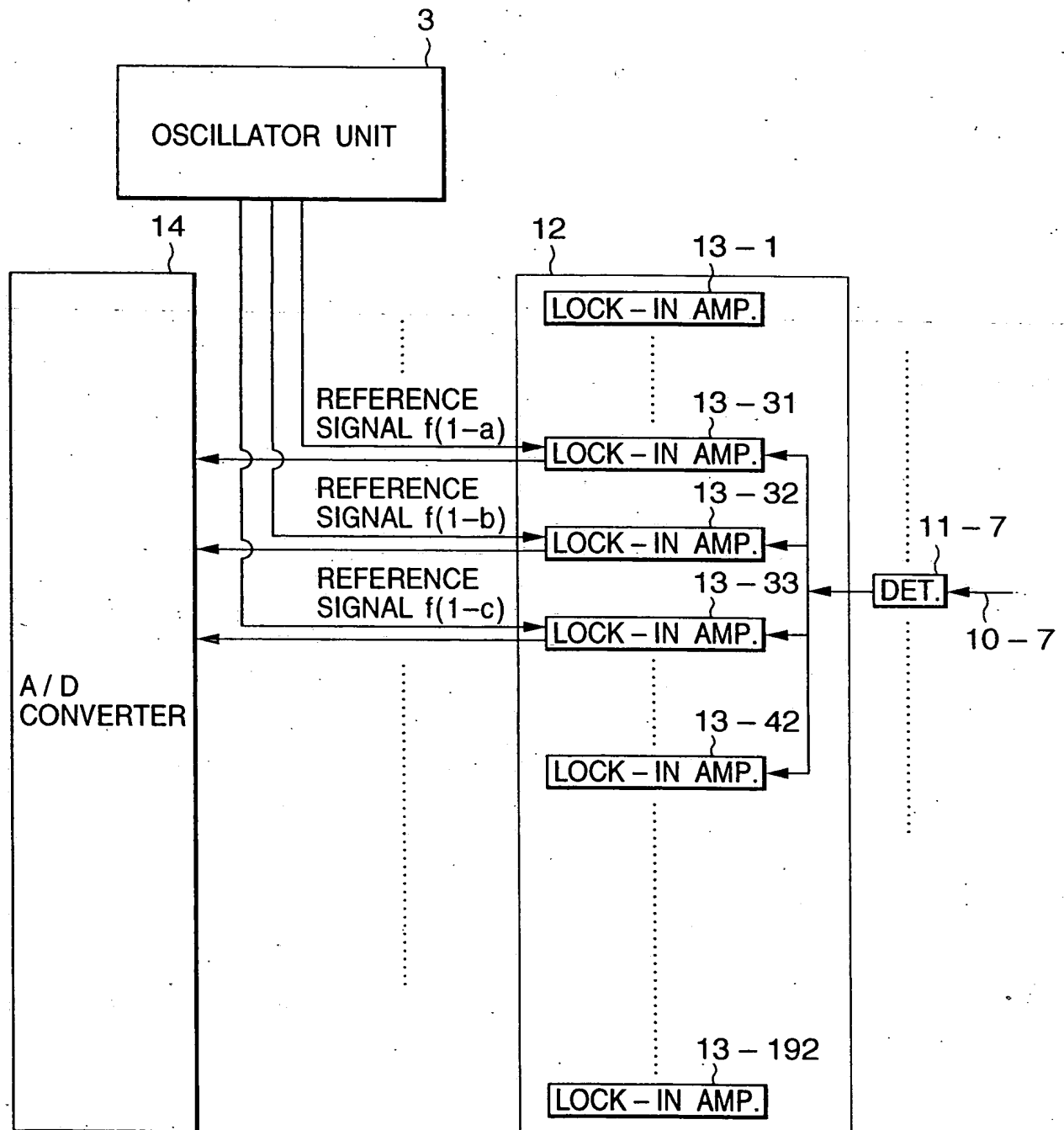


FIG. 8

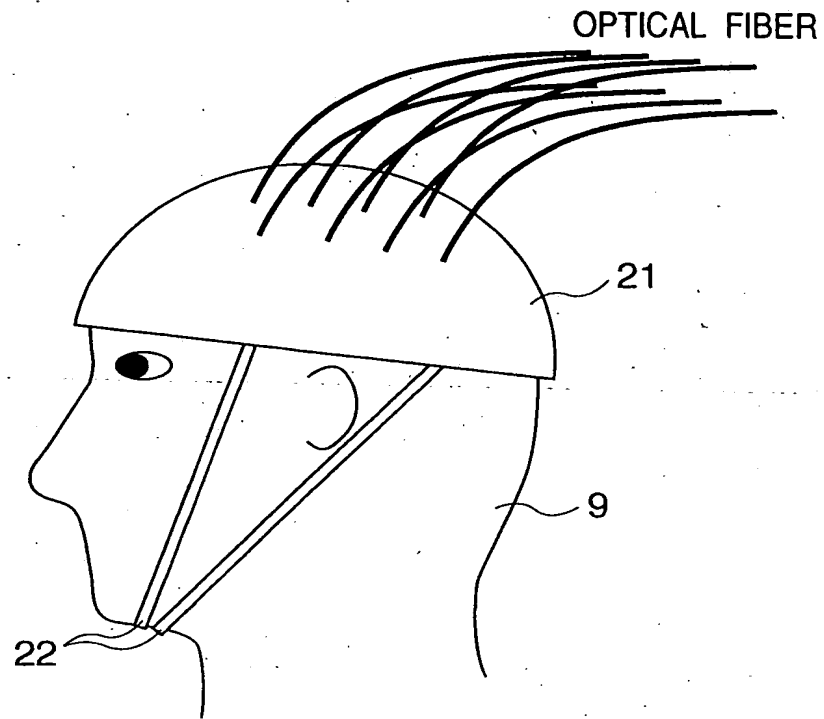


FIG. 9

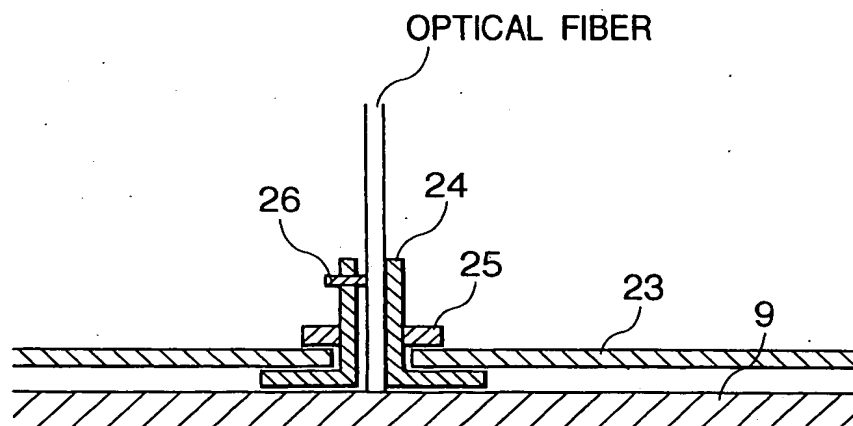


FIG. 10

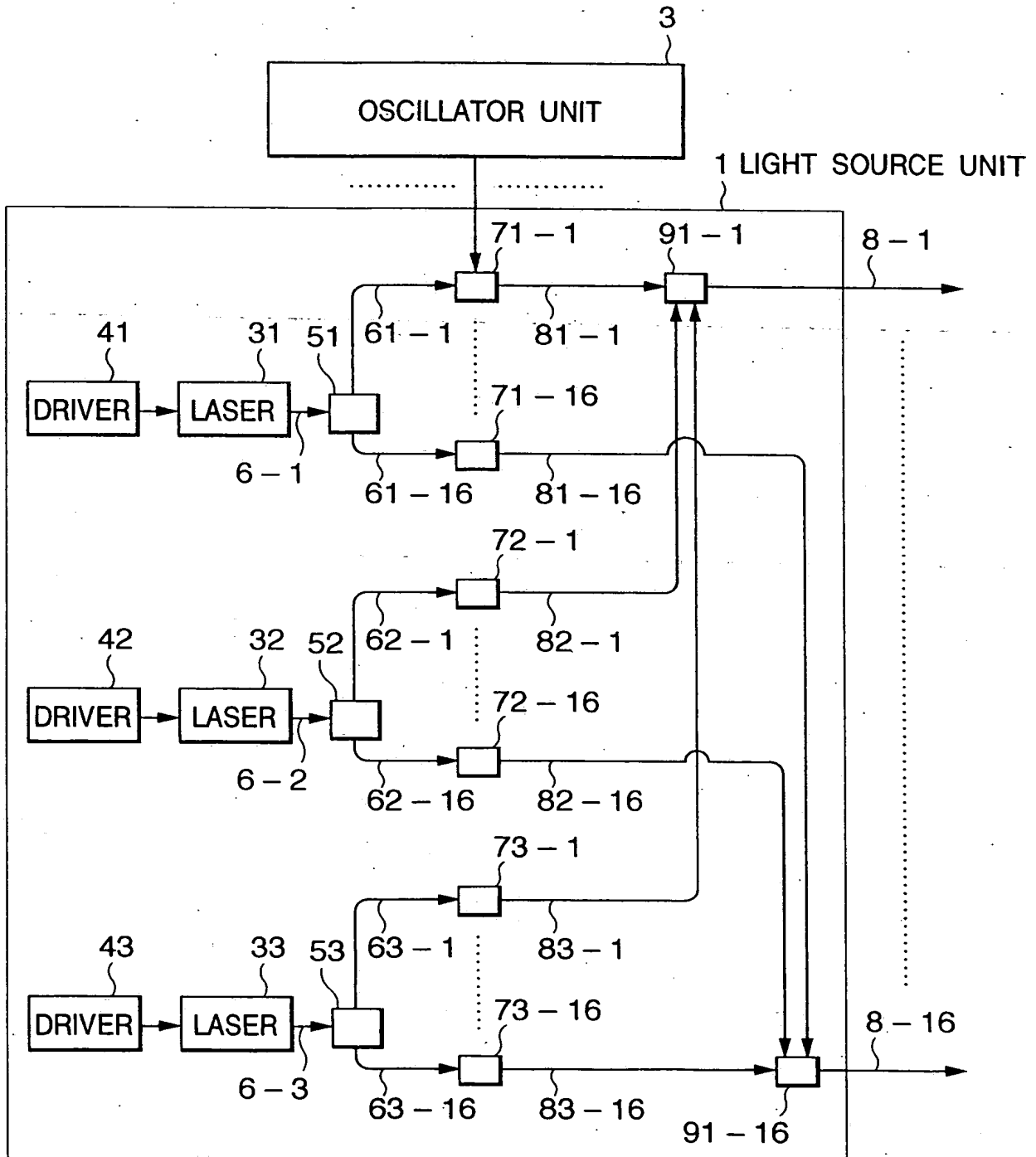


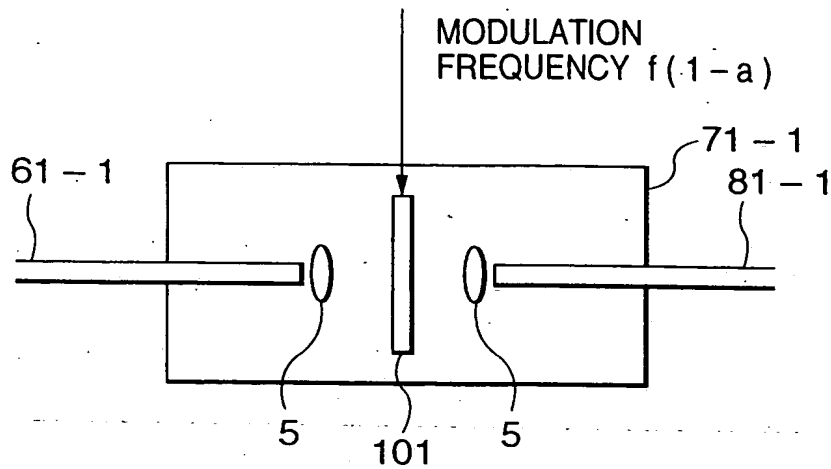
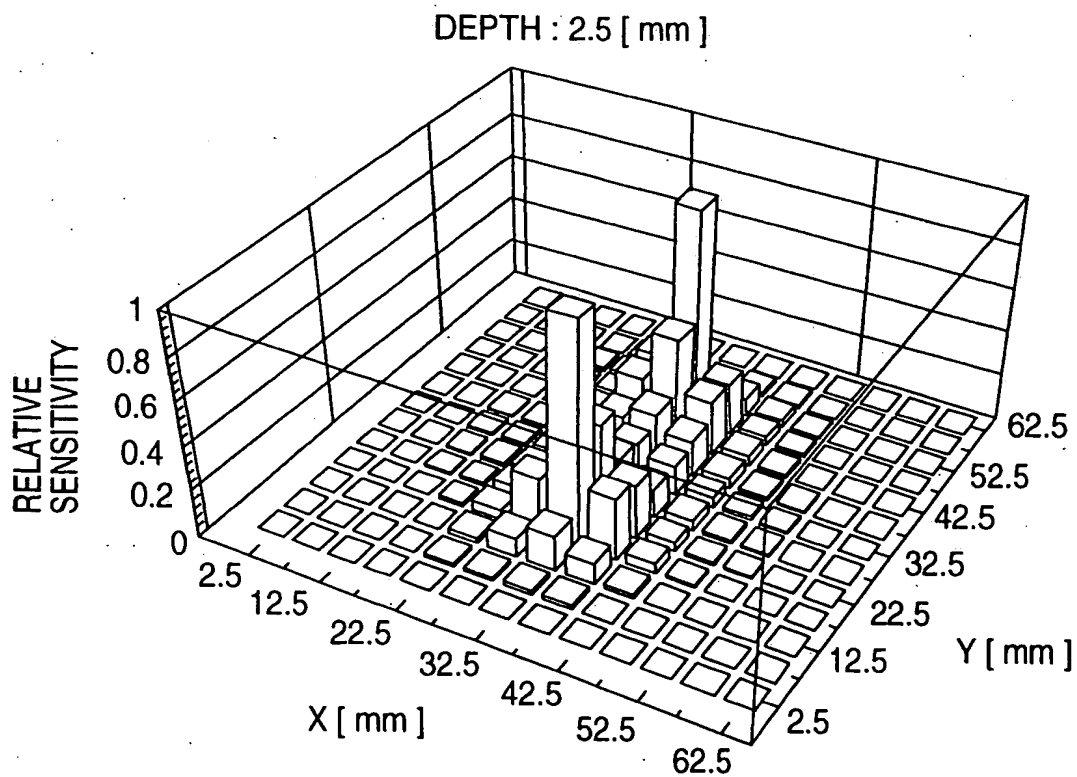
FIG. 11**FIG. 12**

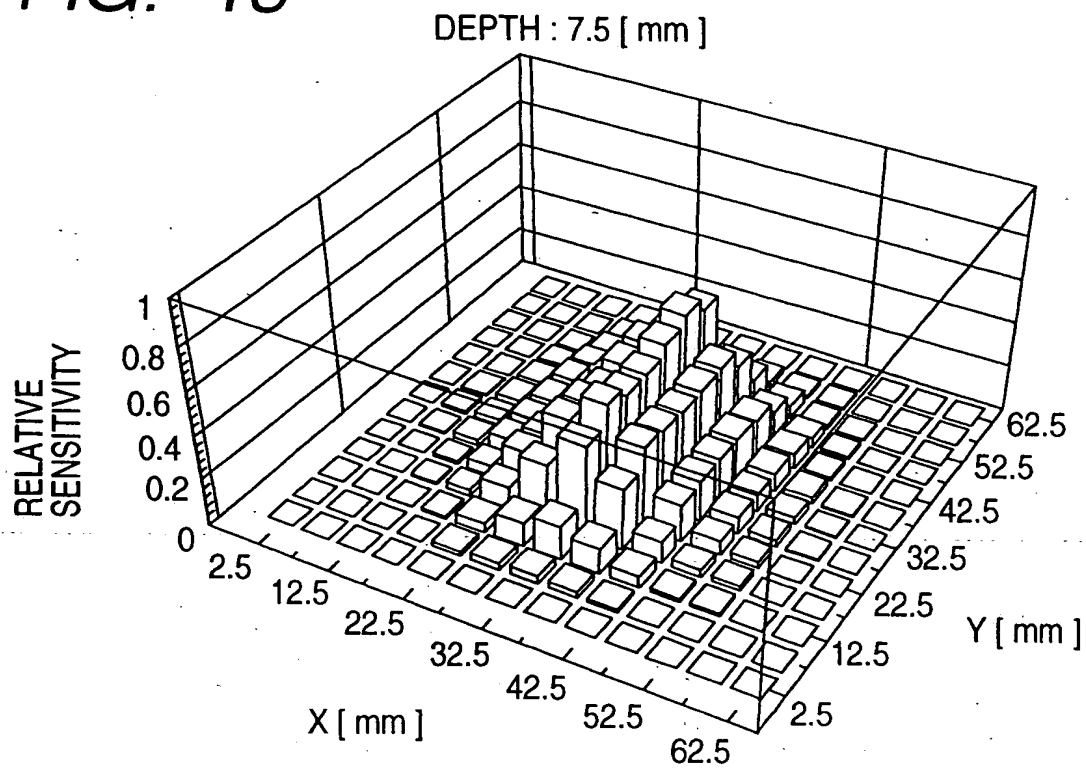
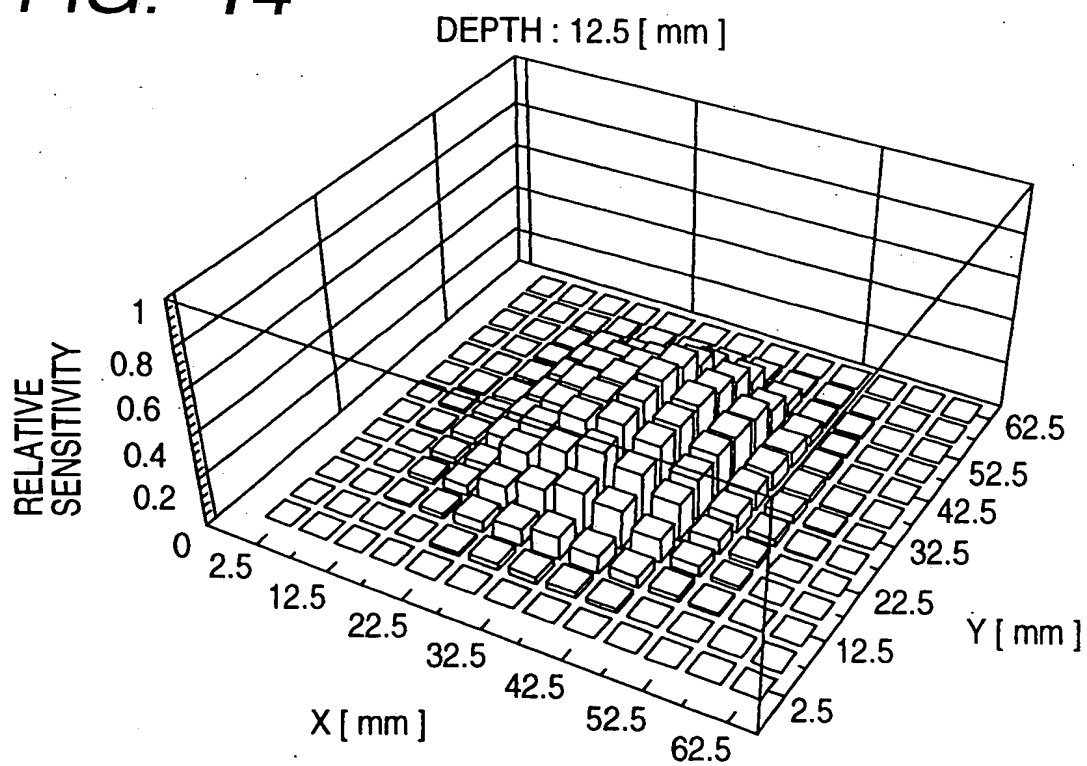
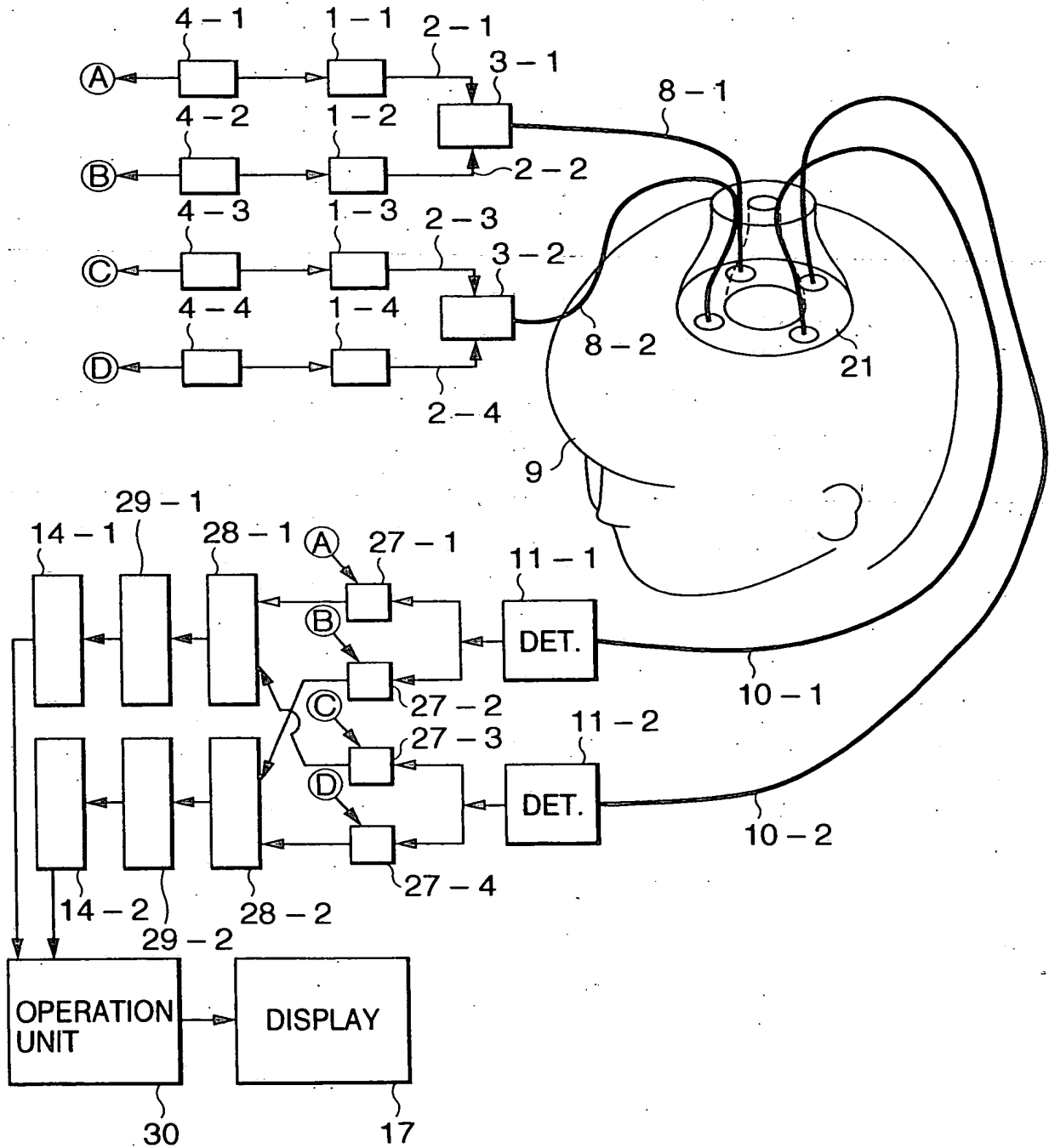
FIG. 13**FIG. 14**

FIG. 15



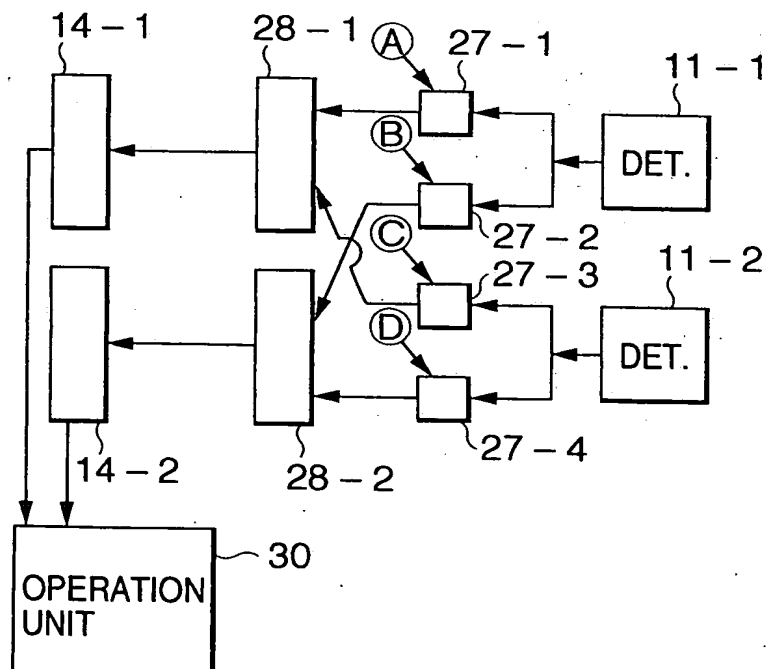


FIG. 18

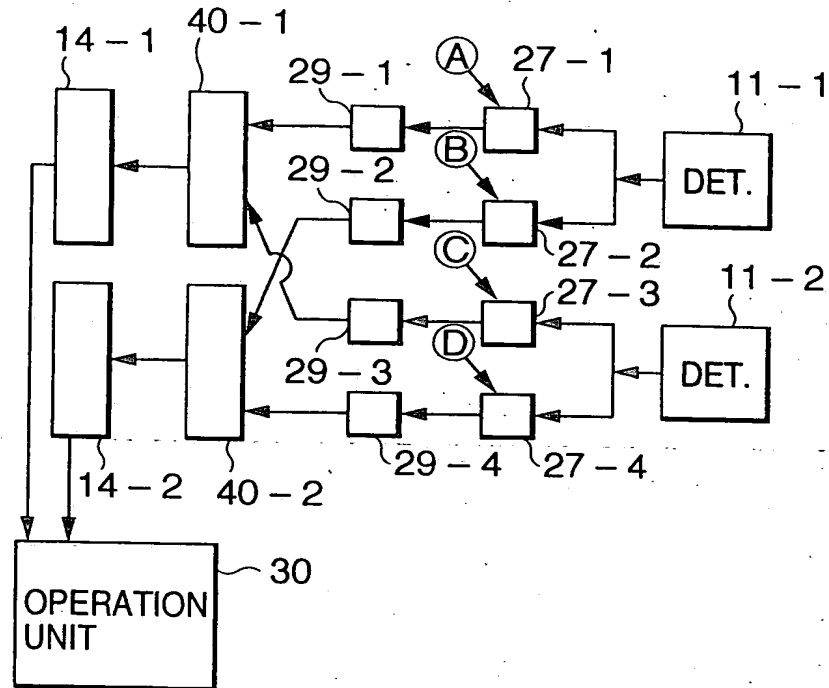


FIG. 19

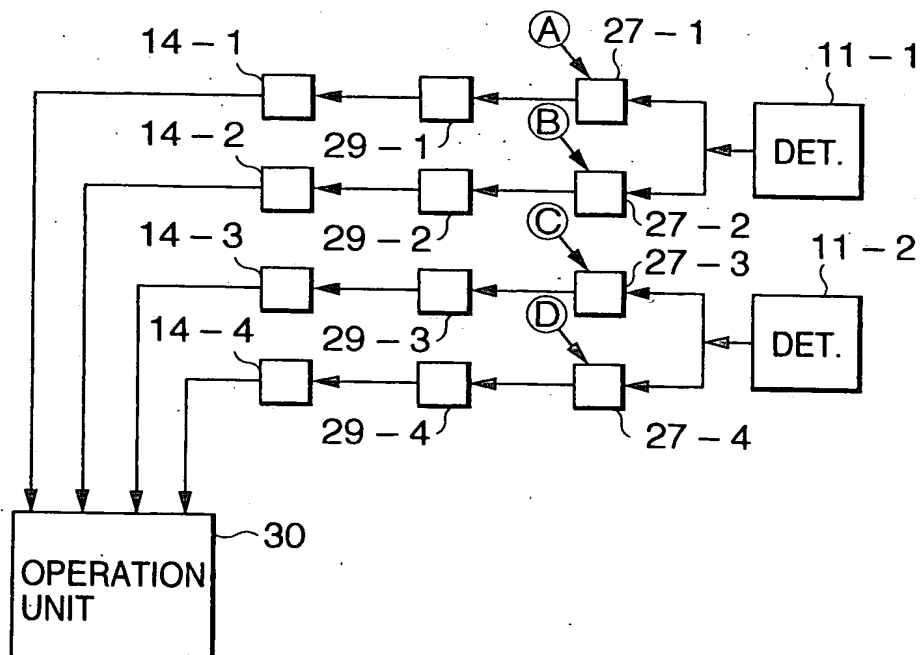


FIG. 20

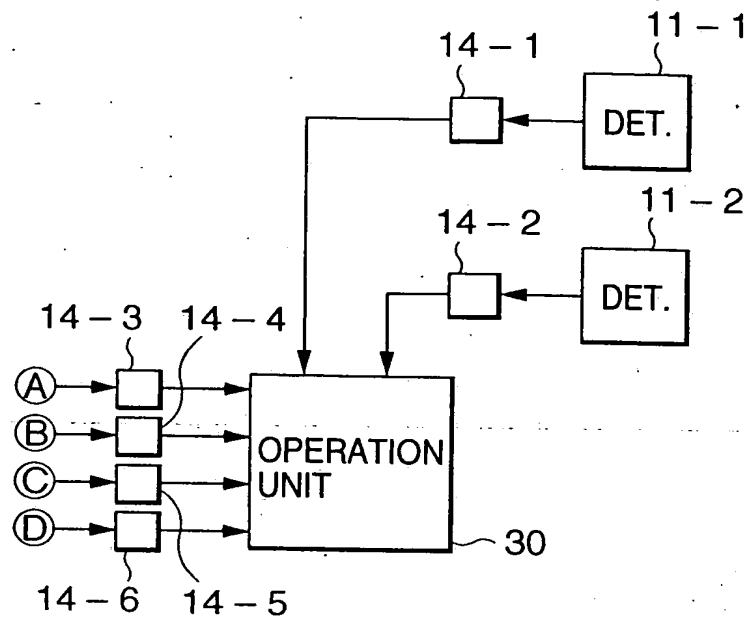


FIG. 21

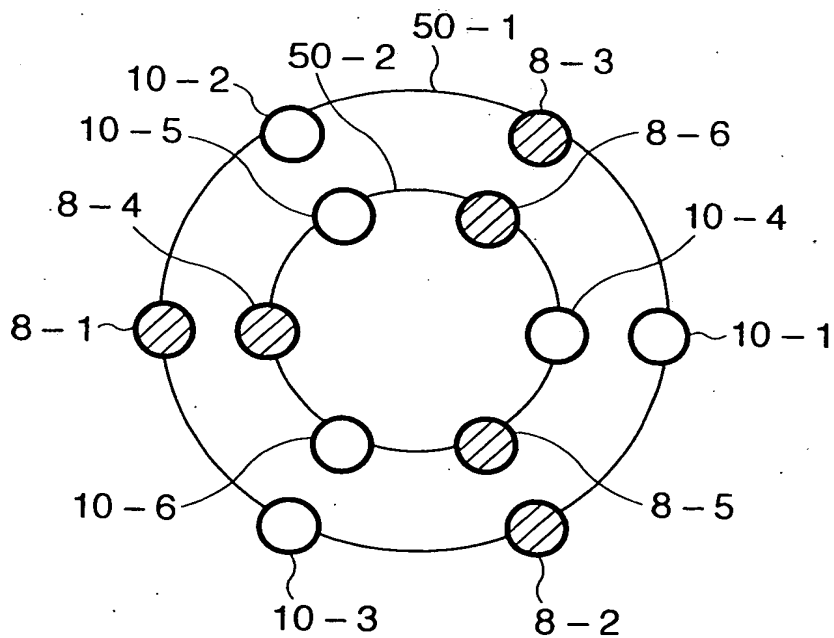


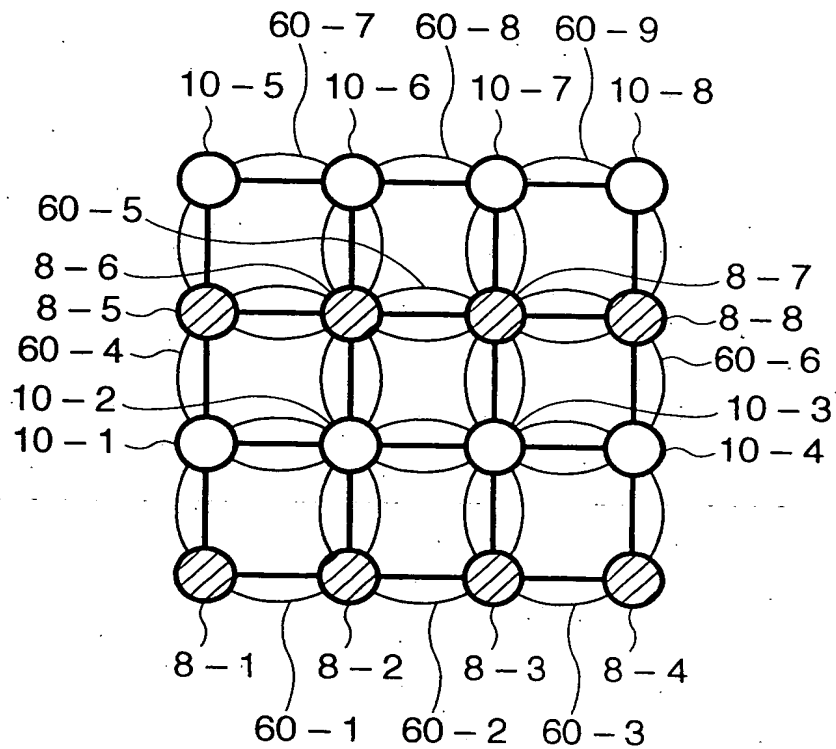
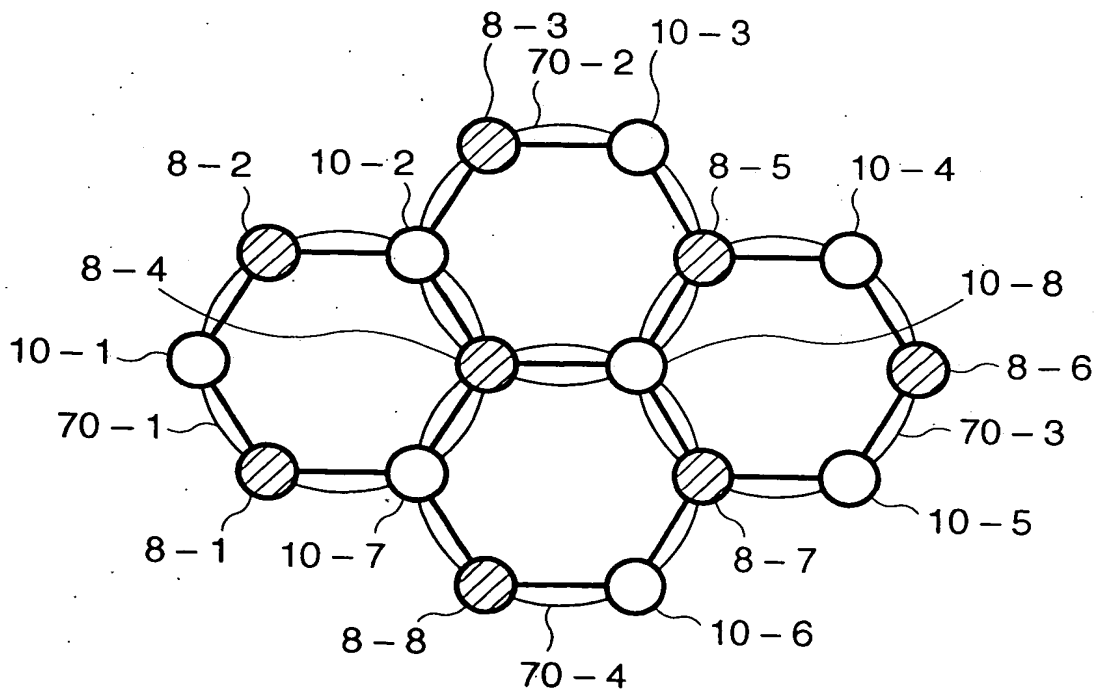
FIG. 22**FIG. 23**

FIG. 24

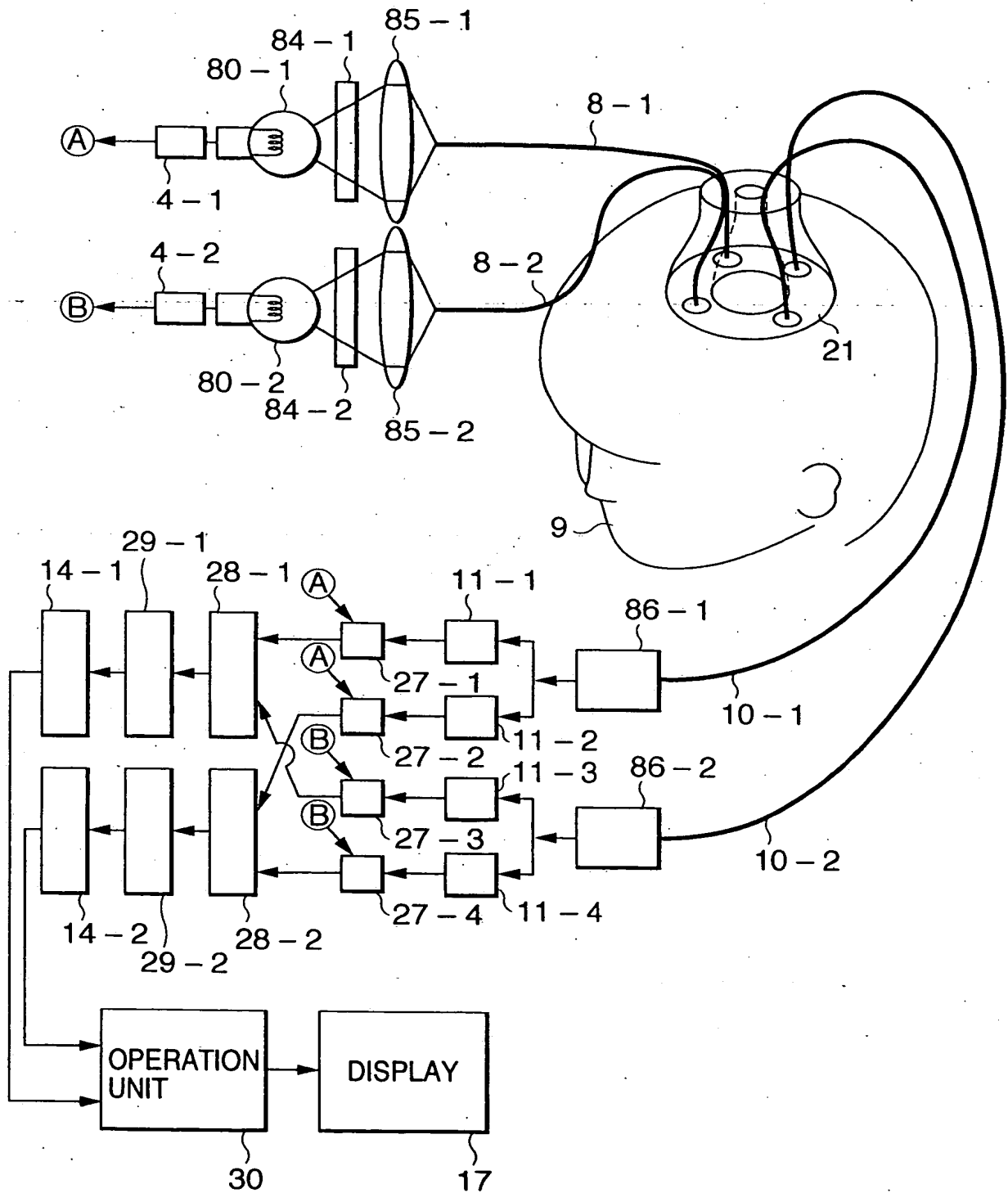


FIG. 25

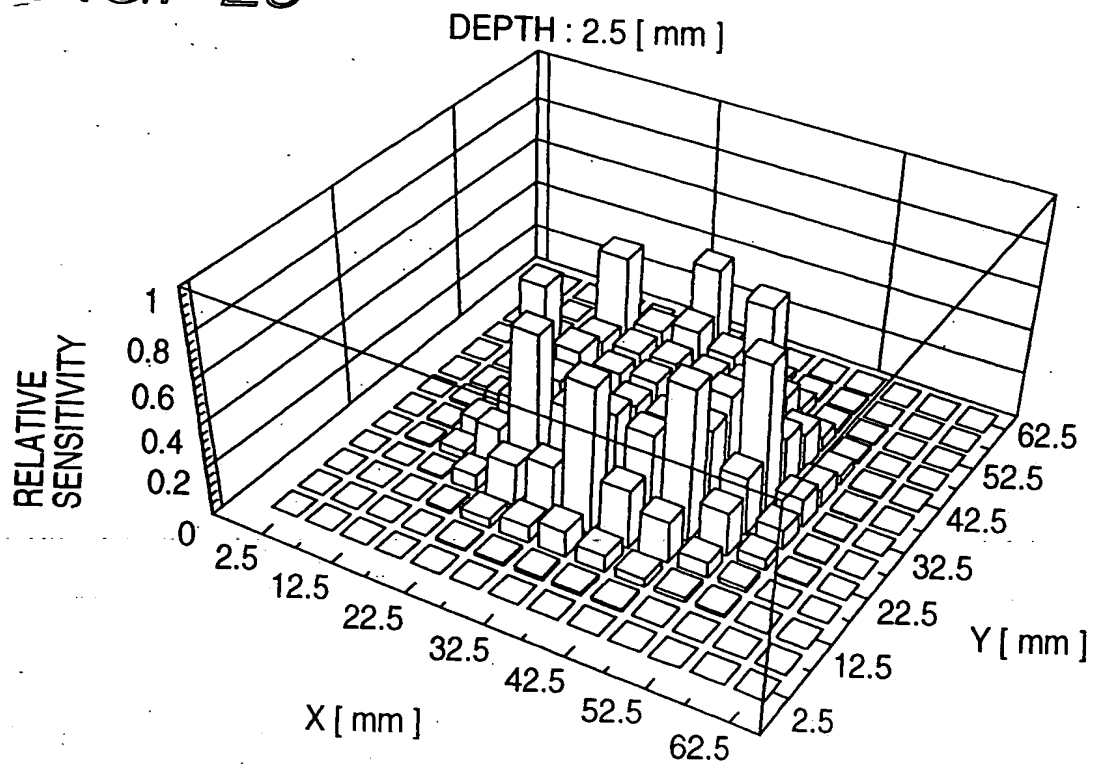


FIG. 26

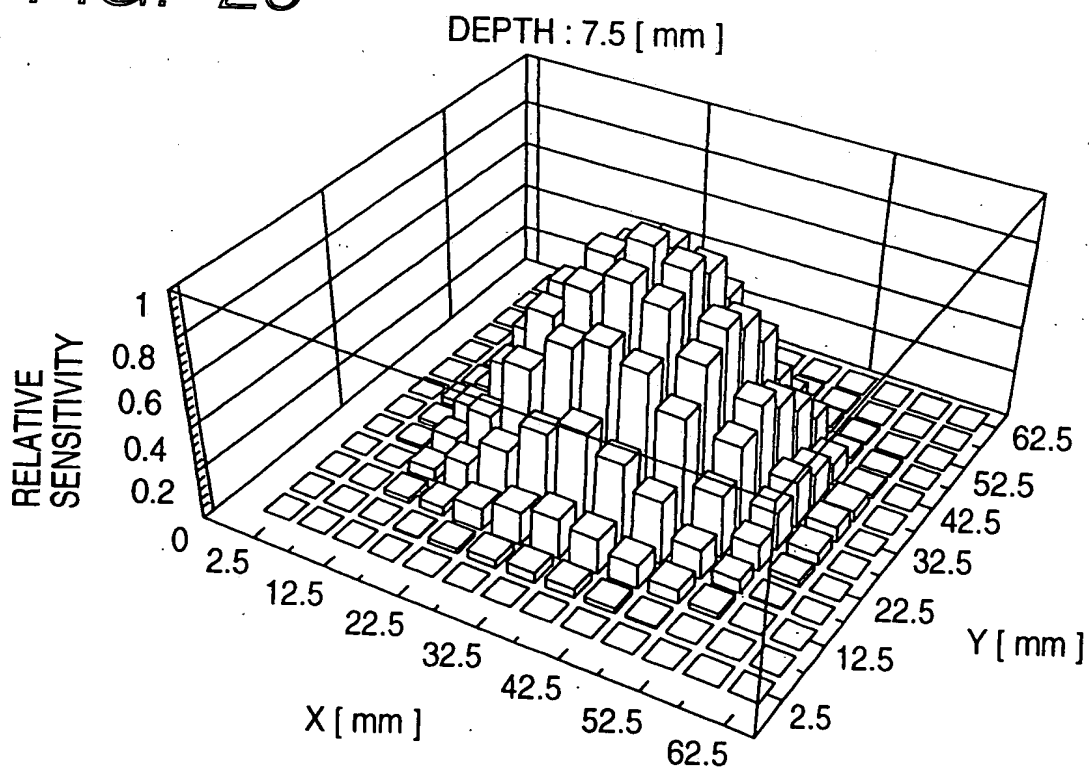


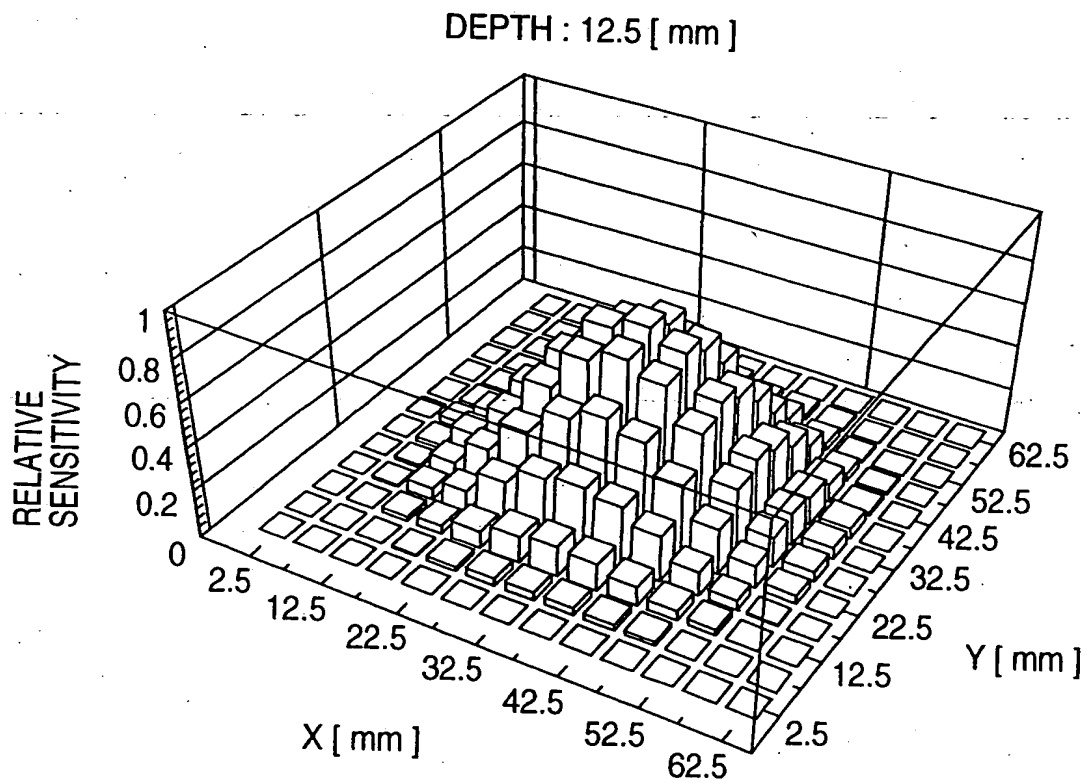
FIG. 27

FIG. 28

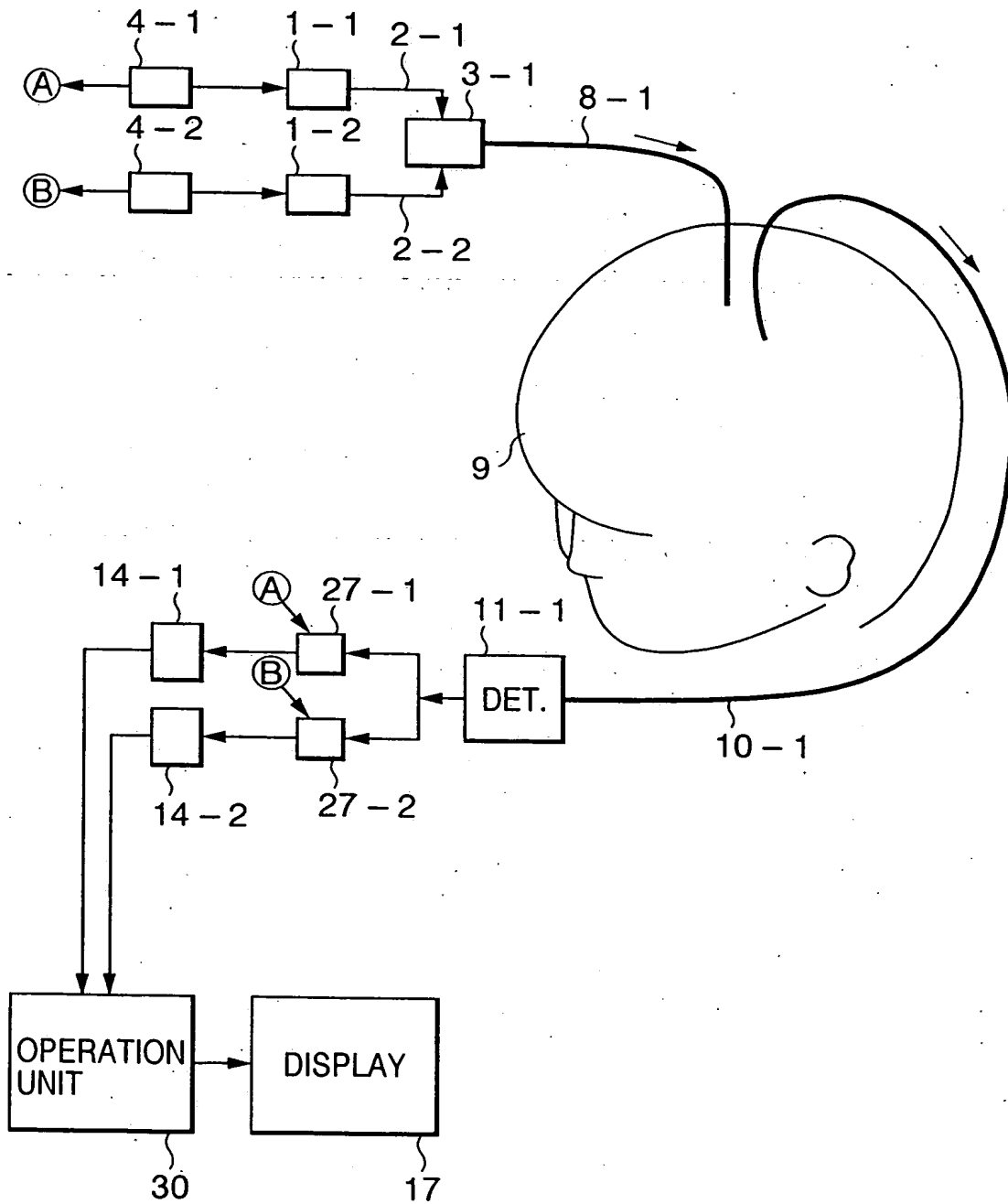


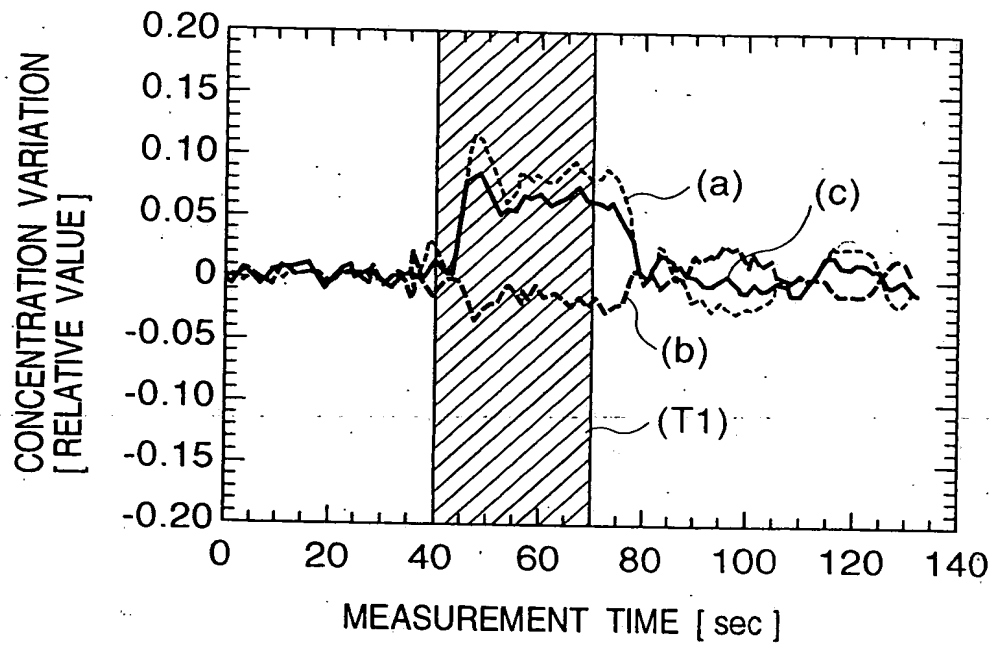
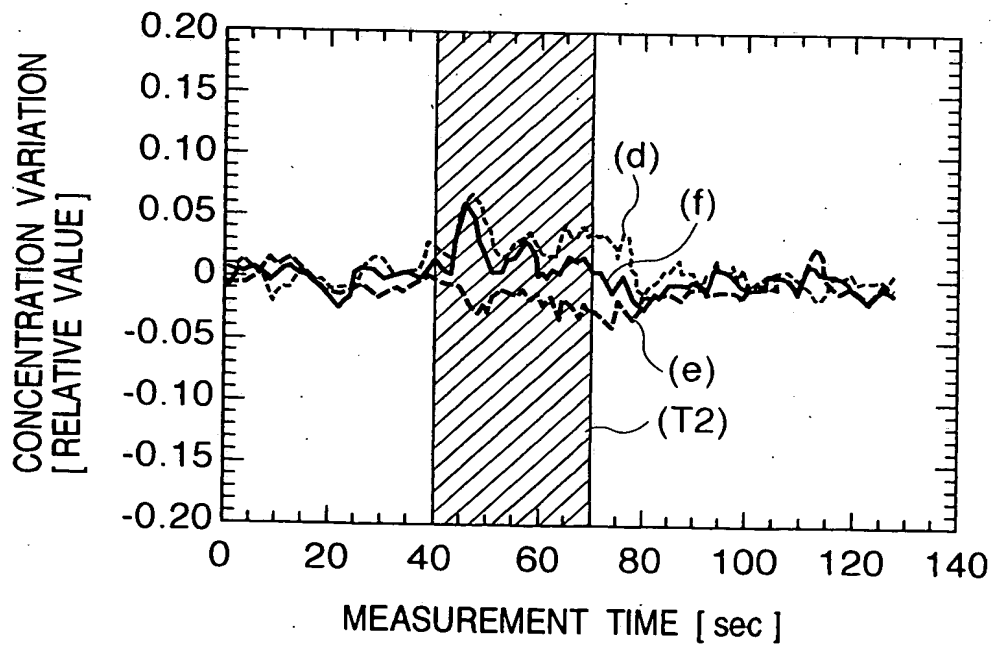
FIG. 29*FIG. 30*

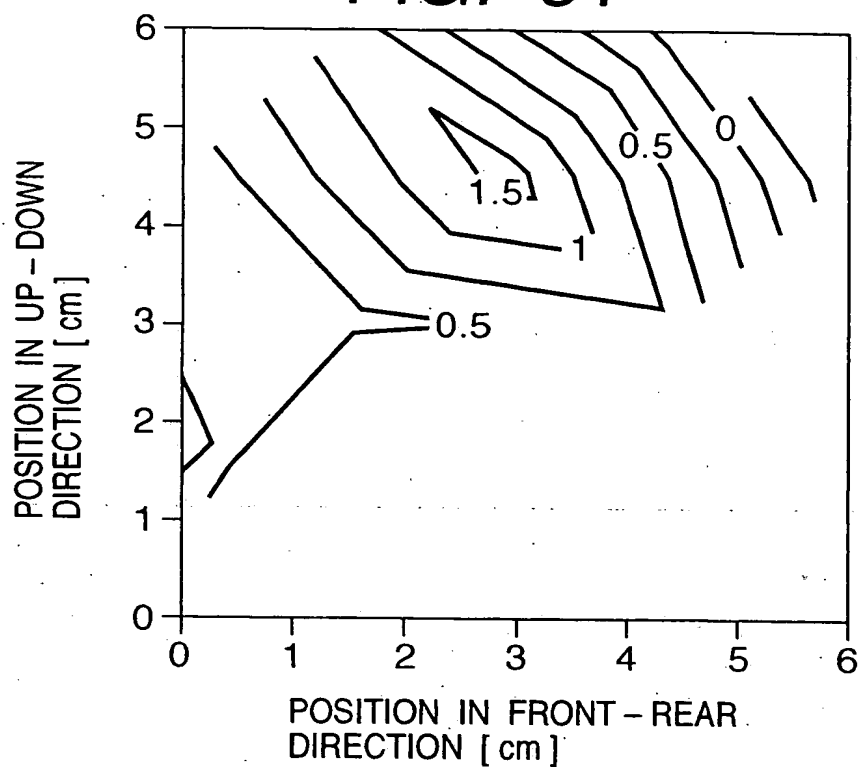
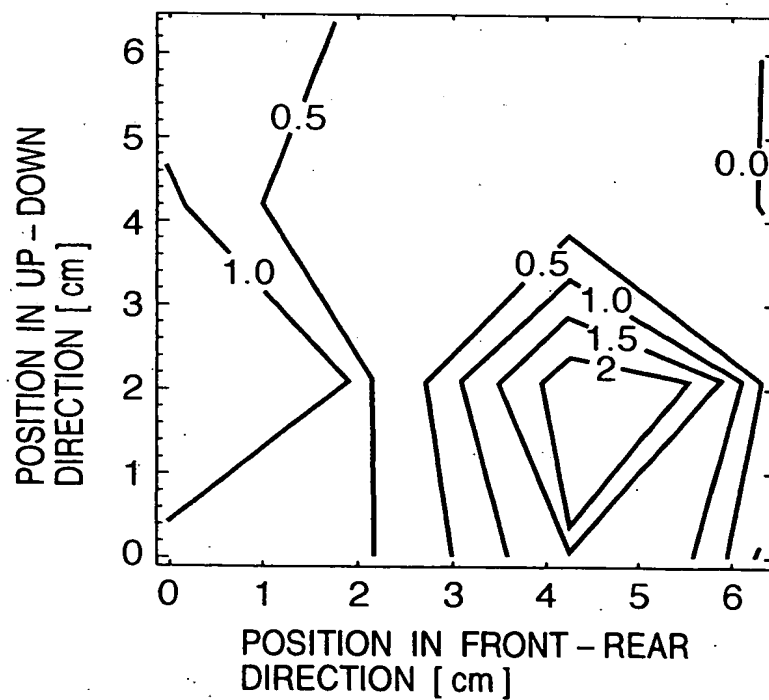
FIG. 31**FIG. 32**

FIG. 33

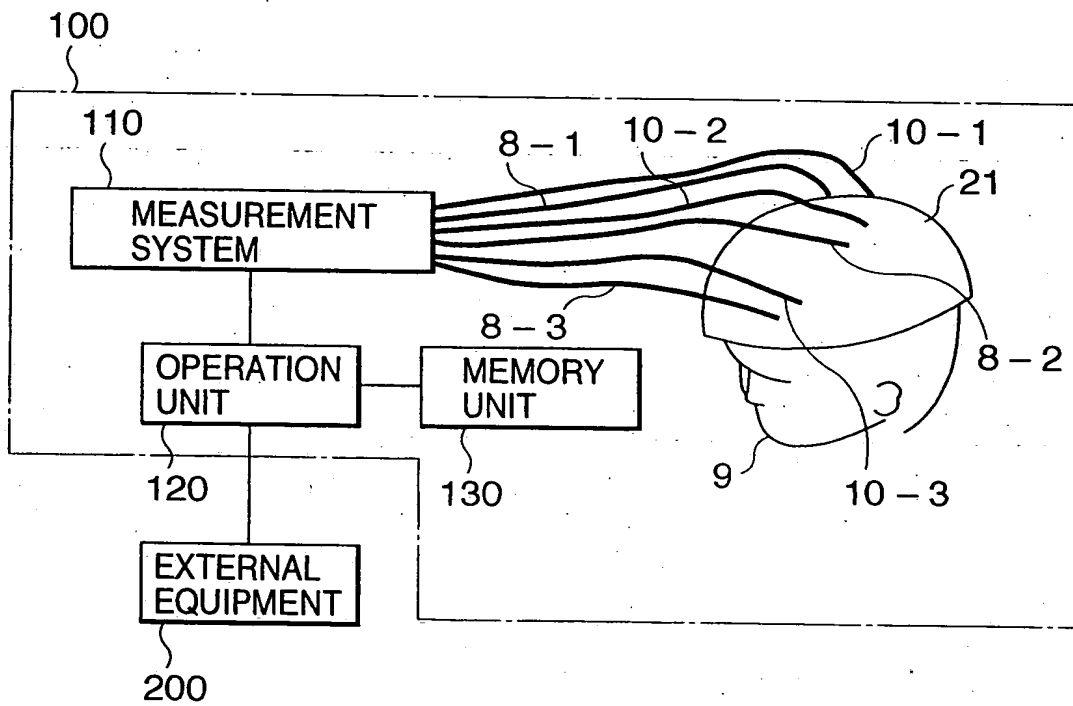


FIG. 34

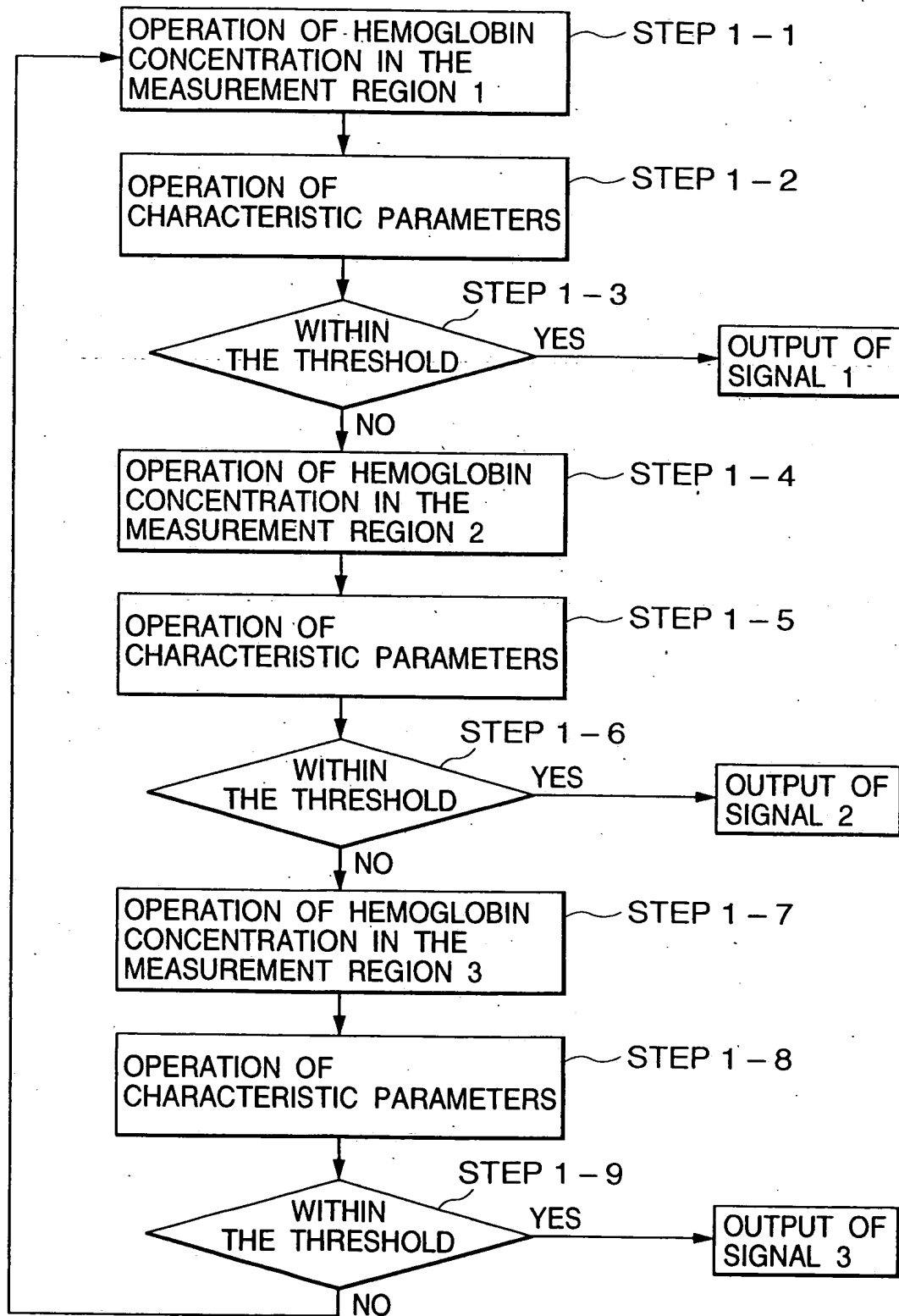


FIG. 35

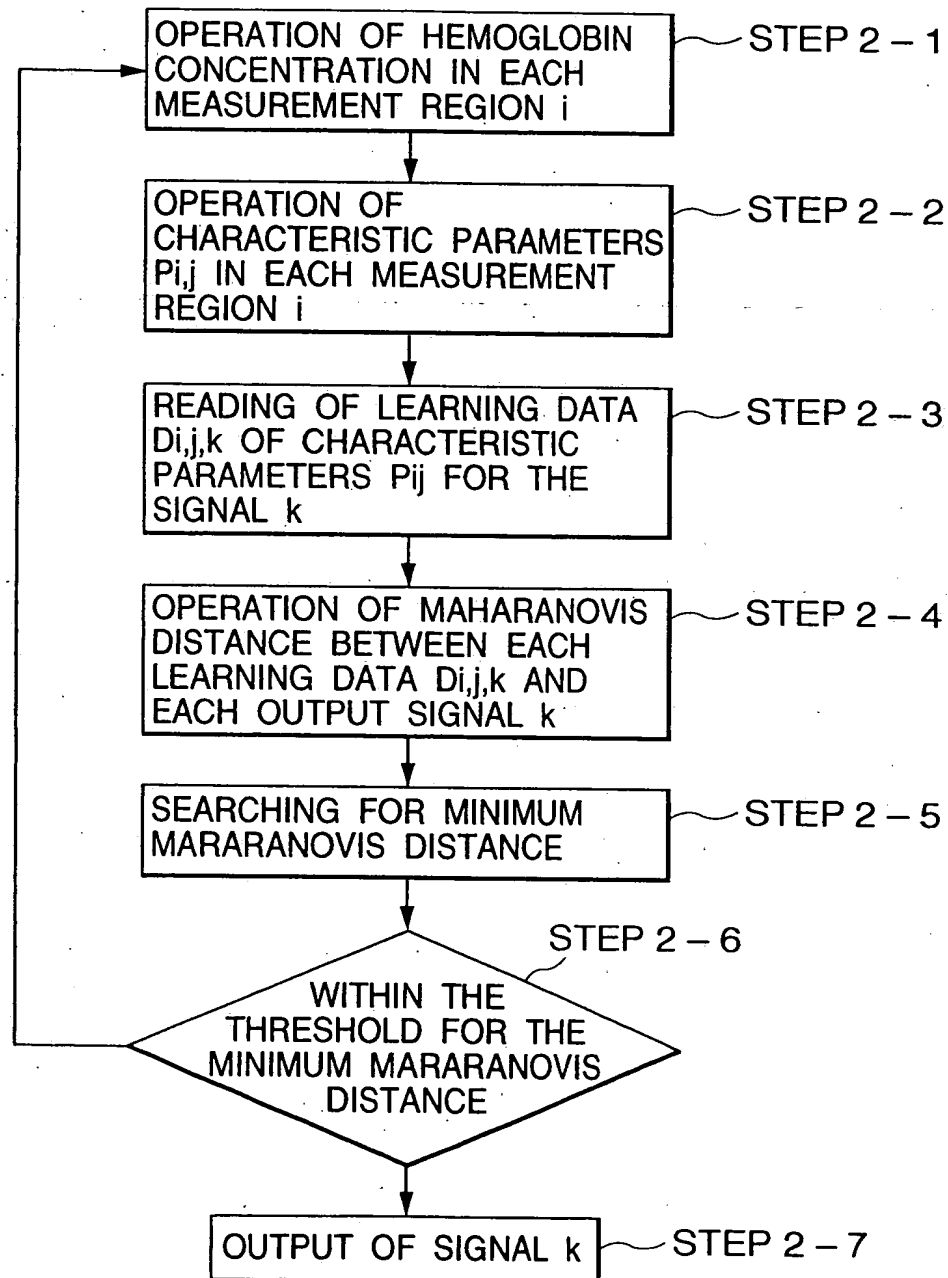


FIG. 36

CHARACTERISTIC PARAMETER j MESUREMENT REGION i	1	2	m - 1	m
	1	2	m - 1	m
1	$S_{1,1,k}$ $A_{1,1,k}$	$S_{1,2,k}$ $A_{1,2,k}$	$S_{1,m-1,k}$ $A_{1,m-1,k}$	$S_{1,m,k}$ $A_{1,m,k}$
2	$S_{2,1,k}$ $A_{2,1,k}$	$S_{2,2,k}$ $A_{2,2,k}$	$S_{2,m-1,k}$ $A_{2,m-1,k}$	$S_{2,m,k}$ $A_{2,m,k}$
⋮	⋮	⋮	⋮	⋮	⋮
n - 1	$S_{n-1,1,k}$ $A_{n-1,1,k}$	$S_{n-1,2,k}$ $A_{n-1,2,k}$	$S_{n-1,m-1,k}$ $A_{n-1,m-1,k}$	$S_{n-1,m,k}$ $A_{n-1,m,k}$
n	$S_{n,1,k}$ $A_{n,1,k}$	$S_{n,2,k}$ $A_{n,2,k}$	$S_{n,m-1,k}$ $A_{n,m-1,k}$	$S_{n,m,k}$ $A_{n,m,k}$

FIG. 37

